

# Entry-wise application of non-linear functions on orthogonally invariant random matrices

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joint work with Alexander Wendel  
arXiv:2412.06943

supported by the DFG project “Free probability aspects of neural networks”

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## Question

How does this change the eigenvalue distribution, asymptotically, if  $N \rightarrow \infty$ ?

# What assumptions should we make about our random matrices $X_N$

## previous work

- *kernel matrices*:  
El Karou 2010; Cheng and Singer 2013; Fan and Montanari 2019
- *covariance matrices*:  
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Our general setting

orthogonally invariant random matrices

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Typical examples (say, symmetric real random matrices)

- given by density of the form

$$\exp(-N\text{Tr}(q(X_N))) dX_N$$

- given as polynomials in independent GOEs

$$p(A_N, B_N, \dots, D_N)$$

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Properties of this class of random matrices

- orthogonal invariance: entries of  $X_N$  have the same joint distribution as entries of  $OX_NO^T$  for any orthogonal  $O$
- existence of scaled limit of correlations ( $c_n$  are classical cumulants)

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has also cyclic structure.



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- probably in many physics papers on a non-rigorous level???
- in particular: are there precise statements in the literature for the orthogonal case for the case of several cycles?

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## Relation between free and classical cumulants

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and the  $\kappa_n$  are the free cumulants of the asymptotic eigenvalue distribution of  $X_N$ .

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How does this change the eigenvalue distribution, asymptotically, if  $N \rightarrow \infty$ ?

## Theorem

- ① *The only cumulants which make asymptotically a contribution in the calculation of the moments of  $\mathbb{E}[\text{tr}(Y_N^n)]$  are those with a cyclic index structure,*

$$\kappa_n^f := \lim_{N \rightarrow \infty} N^{n-1} c_n(y_{i_1 i_2}, y_{i_2 i_3}, \dots, y_{i_n i_1}) \quad \text{all } i_k \text{ distinct.}$$

*Those  $\kappa_n^f$  are thus the free cumulants of the asymptotic eigenvalue distribution of the random matrix  $Y_N$ .*

- ② *We have the following relation between the free cumulants  $\kappa_n$  of the asymptotic eigenvalue distribution of  $X_N$  and the free cumulants  $\kappa_n^f$  of the asymptotic eigenvalue distribution of the random matrix  $Y_N$ :*

- ①  $\kappa_1^f = 0$ ;  
②  $\kappa_2^f = c_2(f(g), f(g)) = \mathbb{E}[f(g)^2] - \mathbb{E}[f(g)]^2$ ;  
③ for  $n \geq 3$ ,

$$\kappa_n^f = \kappa_n \cdot \mathbb{E}[f'(g)]^n;$$

*where  $g$  is a Gaussian random variable with mean zero and variance  $\kappa_2$ .*

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## Theorem (Formula of Leonov and Shiryaev)

$$c_m(a_1 \cdots a_{i(1)}, \dots, a_{i(m-1)+1} \cdots a_{i(m)}) = \sum_{\substack{\pi \in P(n) \\ \pi \vee \tau = 1_n}} c_\pi[a_1, \dots, a_n]$$

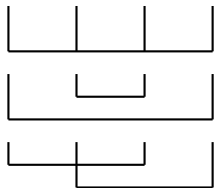
where

$$\tau = \{(1, \dots, i(1)), \dots, (i(m-1) + 1, \dots, i(m))\} \in \mathcal{P}(n).$$



assume  $c_1(a_i) = 0$ ; then

$$c_2(a_1 a_2, a_3 a_4) = c_4(a_1, a_2, a_3, a_4) + c_2(a_1, a_4) c_2(a_2, a_3) + c_2(a_1, a_3) c_2(a_2, a_4)$$



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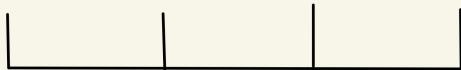
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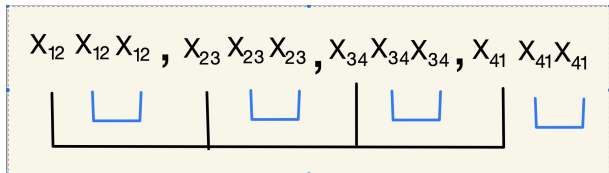
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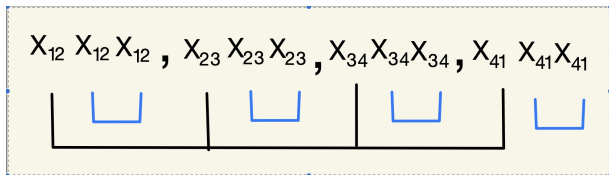
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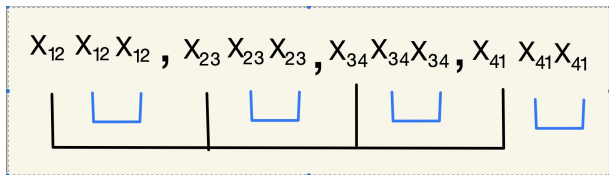
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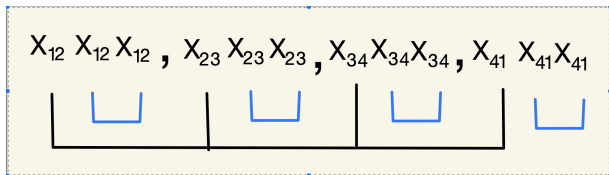
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However, in the case with subcycles

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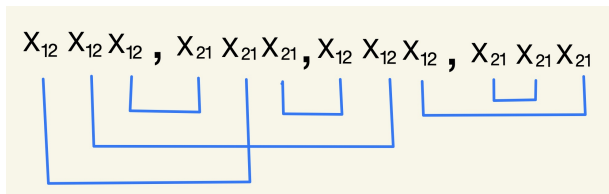
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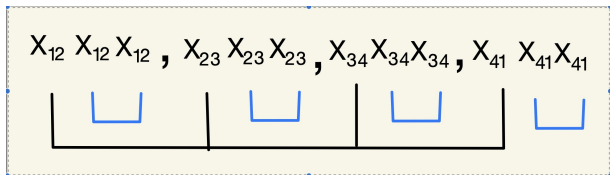
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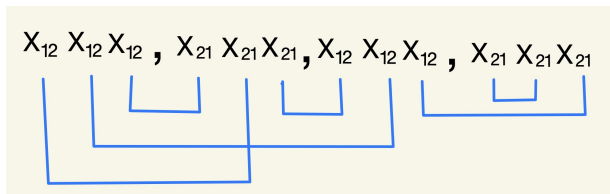
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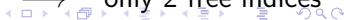
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$$c_4(y_{12}, y_{21}, y_{12}, y_{21}) \sim N^4 (N^{-1})^6 = N^{-2} \quad \longrightarrow \quad \text{only 2 free indices}$$



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But this is still small enough to not contribute to  $\mathbb{E}[\text{tr}(Y_N^n)]$ .



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- The  $\kappa_n^f$  are given by

- ▶ for  $n = 1$

$$\kappa_1^f = 0$$

- ▶ for  $n = 2$

$$\kappa_2^f = c_2(f(g), f(g))$$

- ▶ for  $n \geq 3$ ,

$$\kappa_n^f = \kappa_n \cdot \mathbb{E}[f'(g)]^n;$$

where  $g$  is a Gaussian random variable with mean zero and variance  $\kappa_2$ .

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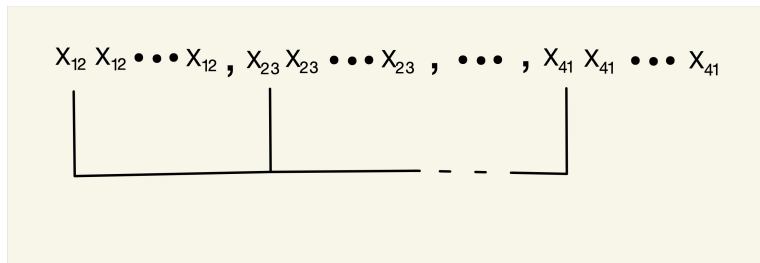
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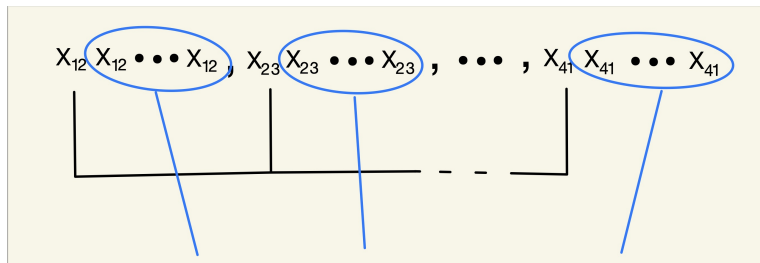
$\kappa_4$   $m_1$

$m_2$

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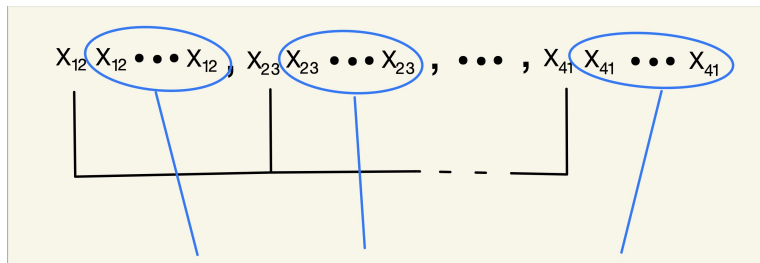
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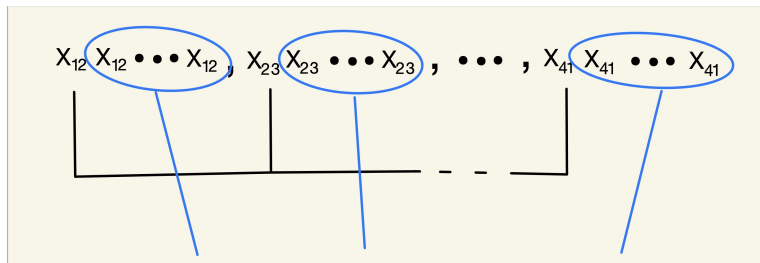
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$$\kappa_4 \quad m_1 \quad \mathbb{E}[g^{m_1-1}] \quad m_2 \quad \mathbb{E}[g^{m_2-1}] \quad \dots \quad m_4 \quad \mathbb{E}[g^{m_4-1}]$$

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$$\kappa_4 \quad \mathbb{E}[f'_1(g)] \quad \mathbb{E}[f'_2(g)] \quad \dots \quad \mathbb{E}[f'_4(g)]$$

where  $g$  is a Gaussian random variable with mean zero and variance  $\kappa_2$ .



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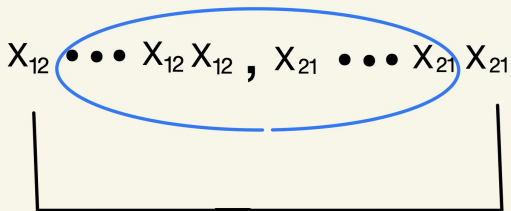
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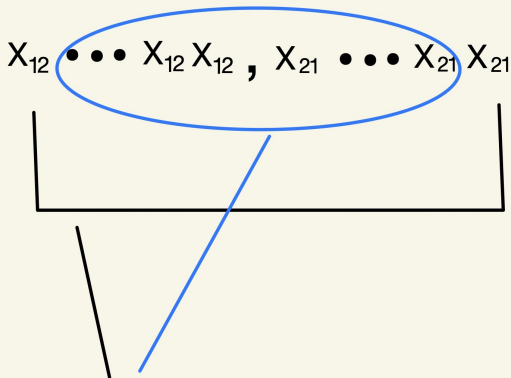
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where  $g$  is a Gaussian random variable with mean zero and variance  $\kappa_2$ .

# Gaussian equivalence principle

## Corollary

Let  $X_N$  and  $Y_N$  be as above. Then the non-linear random matrix model  $Y_N$  has the same asymptotic eigenvalue distribution as the linear model

$$\hat{Y}_N := \theta_1 X_N + \theta_2 Z_N,$$

where  $Z_N$  is a symmetric standard GOE random matrix which is independent from  $X_N$  and where

$$\theta_1 := \mathbb{E}[f'(g)]$$

and

$$\theta_2 := \sqrt{\mathbb{E}[f(g)^2] - \mathbb{E}[f(g)]^2 - \kappa_2 \mathbb{E}[f'(g)]^2},$$

where  $g$  is a Gaussian random variable with mean zero and variance  $\kappa_2$ .

## Example: The ReLU function

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$$f(x) = \text{ReLU}(x) := \max(0, x).$$

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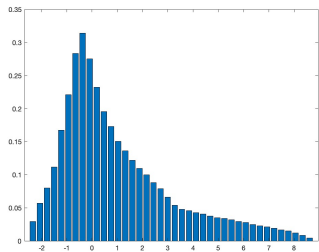
We want to compare

non-linear random matrix  $Y_N = \text{ReLU}(X_N)$

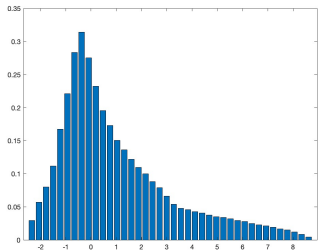
versus

linear Gaussian equivalent  $\hat{Y}_N := \frac{1}{2}X_N + \frac{1}{2}\sqrt{5(1 - 2/\pi)}Z_N$

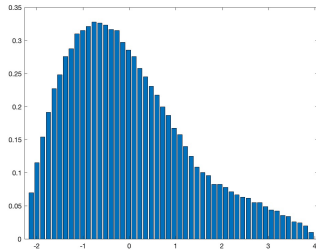
$$X_N = A_N^2 + A_N + B_N A_N \\ + A_N B_N + B_N$$



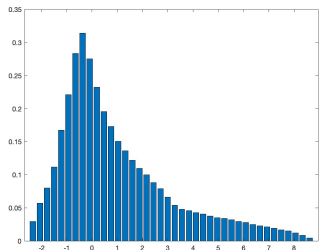
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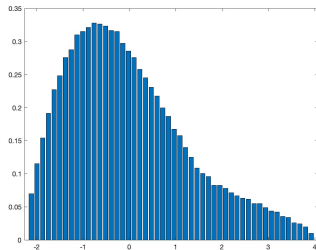
$Y_N$ , after applying ReLU entrywise to  $X_N$



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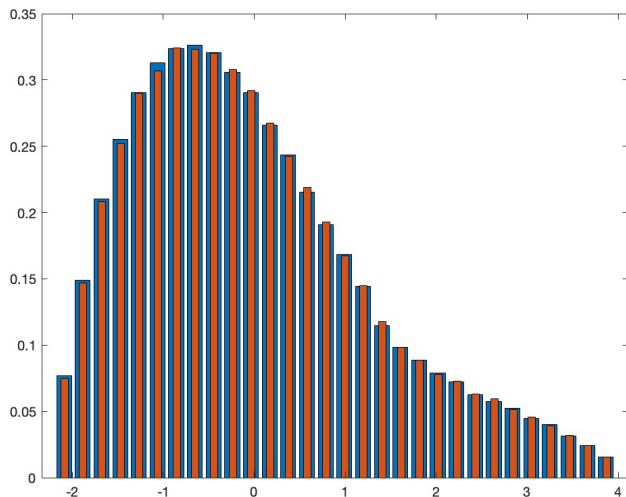


$Y_N$ , after applying ReLU entrywise to  $X_N$



Gaussian equivalent  $\hat{Y}_N := \frac{1}{2}X_N + \frac{1}{2}\sqrt{5(1 - 2/\pi)}Z_N$

# Superposition of the eigenvalues of the non-linear matrix $Y_N$ and of its Gaussian equivalent $\hat{Y}_N$



## Extension to multivariate case

Consider 2 independent matrices

$$X_N^{(1)} = (x_{ij}^{(1)})_{i,j=1}^N \quad \text{and} \quad X_N^{(2)} = (x_{ij}^{(2)})_{i,j=1}^N.$$

and a function (for now, a polynomial)

$$f : \mathbb{R}^2 \rightarrow \mathbb{R}$$

and define the non-linear random matrix  $Y_N = (y_{ij})_{i,j=1}^N$  by

$$y_{ij} = \begin{cases} \frac{1}{\sqrt{N}} f \left( \sqrt{N} x_{ij}^{(1)}, \sqrt{N} x_{ij}^{(2)} \right), & i \neq j \\ 0, & i = j. \end{cases}$$

## Corollary

Let  $X_N^{(1)}$ ,  $X_N^{(2)}$  and  $Y_N$  be as above. Then the non-linear random matrix model  $Y_N$  has the same asymptotic eigenvalue distribution as the linear model

$$\hat{Y}_N := \theta_1 X_N^{(1)} + \theta_2 X_N^{(2)} + \theta Z_N,$$

where  $Z_N$  is a symmetric standard GOE random matrix which is independent from  $X_N^{(1)}$  and  $X_N^{(2)}$  and where

$$\theta_1 := \mathbb{E}[\partial_1 f(g_1, g_2)], \quad \theta_2 := \mathbb{E}[\partial_2 f(g_1, g_2)]$$

and

$$\theta := \sqrt{c_2(f(g_1, g_2), f(g_1, g_2)) - \kappa_2^{(1)} \theta_1^2 - \kappa_2^{(2)} \theta_2^2},$$

where  $g_1$  and  $g_2$  are independent Gaussian random variables with mean zero and variance  $\kappa_2^{(1)}$  and  $\kappa_2^{(2)}$ , respectively.

## Example: the maximum function

The function

$$f(x_1, x_2) = \max(x_1, x_2) = \frac{1}{2}(x_1 + x_2 + |x_1 - x_2|).$$



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$$X_N^{(1)} = \frac{-A_N^2 + B_N}{\sqrt{2}}, \quad X_N^{(2)} = \frac{C_N^4 + C_N D_N + D_N C_N}{\sqrt{12}},$$

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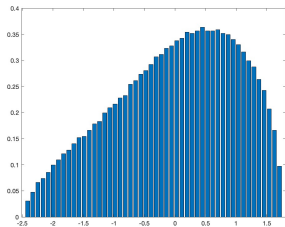
We want to compare

non-linear random matrix  $Y_N = \max(X_N^{(1)}, X_N^{(2)})$

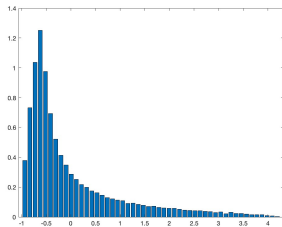
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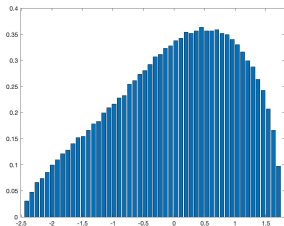
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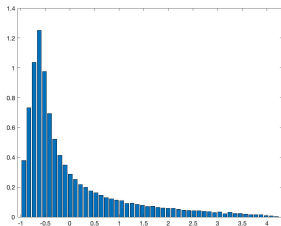
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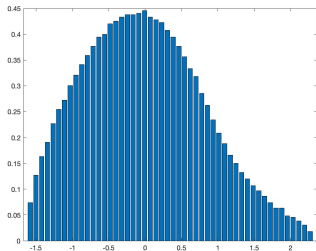
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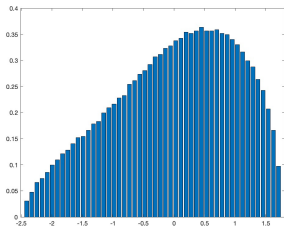
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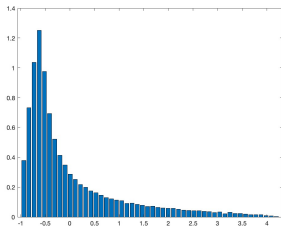
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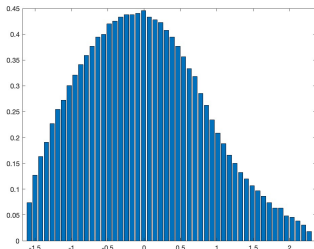
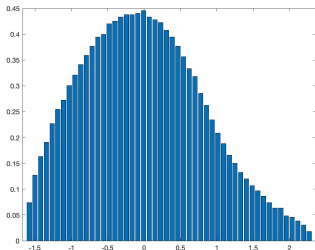


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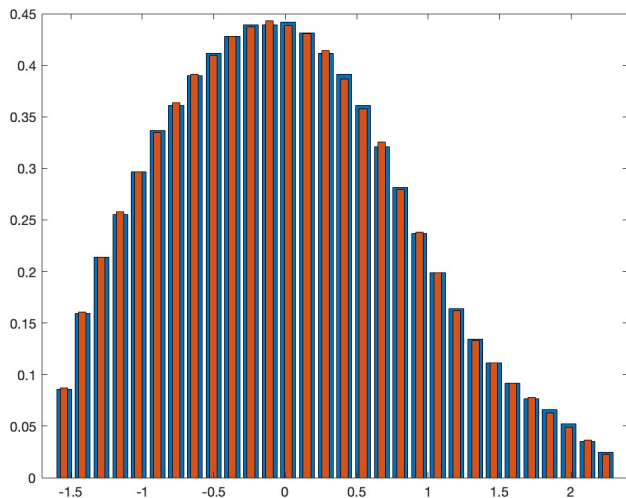


$$Y_N = \max(X_N^{(1)}, X_N^{(2)})$$

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# Superposition of the eigenvalues of the non-linear matrix $Y_N$ and of its Gaussian equivalent $\hat{Y}_N$



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## Example: something more non-linear

The function

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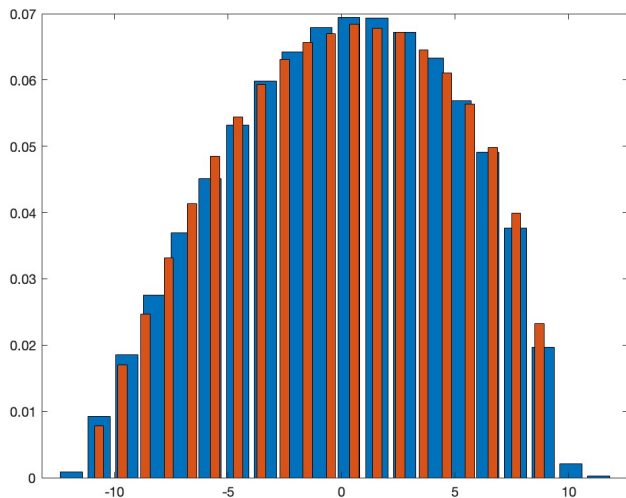
non-linear random matrix  $Y_N = \max(X_1^{(1)}, X_2^{(2)})$

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# Superposition of the eigenvalues of the non-linear matrix $Y_N$ and of its Gaussian equivalent $\hat{Y}_N$



## Extension to multivariate case with correlation

Let  $X_N^{(1)}$  and  $X_N^{(2)}$  be jointly orthogonally invariant random matrices.

$$\kappa_n^{(r_1, \dots, r_n)} := \lim_{N \rightarrow \infty} N^{n-1} c_n(x_{i_1 i_2}^{(r_1)}, x_{i_2 i_3}^{(r_2)}, \dots, x_{i_n i_1}^{(r_n)}).$$

and define the non-linear random matrix  $Y_N = f(X_N^{(1)}, X_N^{(2)}) = (y_{ij})_{i,j=1}^N$  by

$$y_{ij} = \begin{cases} \frac{1}{\sqrt{N}} f\left(\sqrt{N} x_{ij}^{(1)}, \sqrt{N} x_{ij}^{(2)}\right), & i \neq j \\ 0, & i = j. \end{cases}$$

## Corollary

The non-linear random matrix model  $Y_N = f(X_N^{(1)}, X_N^{(2)})$  has the same asymptotic eigenvalue distribution as the linear model

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where  $g_1$  and  $g_2$  are a Gaussian family of random variables with mean zero and covariance

$$c_2(g_1, g_1) = \kappa_2^{(1,1)}, \quad c_2(g_2, g_2) = \kappa_2^{(2,2)}, \quad c_2(g_1, g_2) = \kappa_2^{(1,2)}.$$

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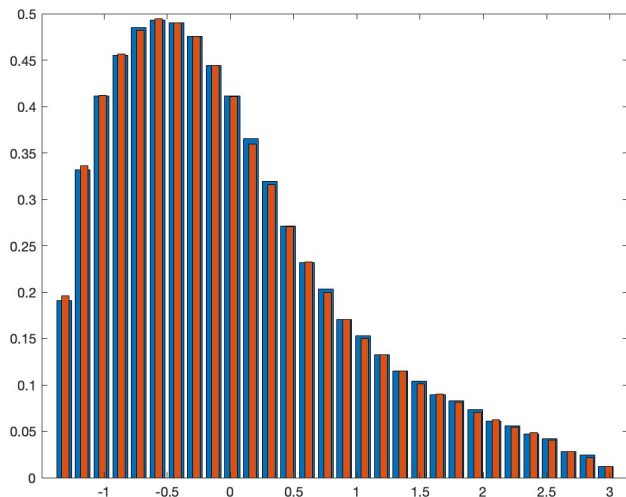
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